

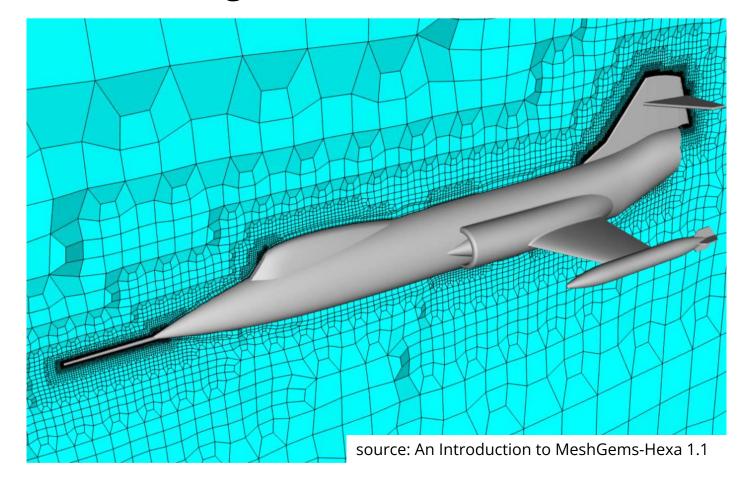
OPTIMAL DUAL SCHEMES FOR ADAPTIVE GRID BASED HEXMESHING

Marco Livesu CNR IMATI, Italy **Luca Pitzalis**University of Cagliari & CRS4, Italy

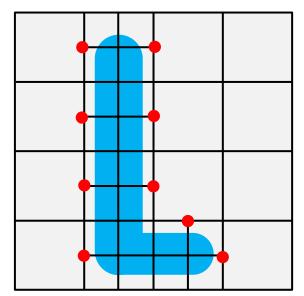
Gianmarco Cherchi University of Cagliari, Italy

Grid-based hexahedral meshing

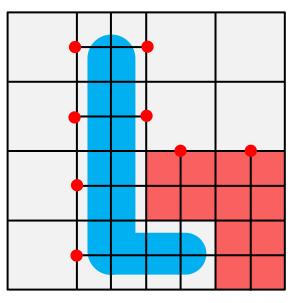
- ▶ The only existing automatic method for "black box" hexahedral meshing
- ► Theoretical breakthrough: dual methods [Maréchal, 2009]



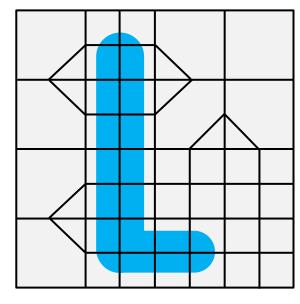
Basics of dual grid-based hexmeshing



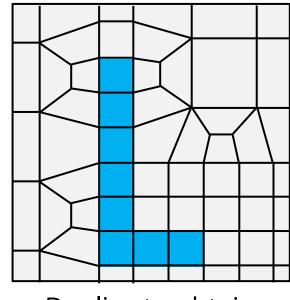
Initialize an adaptive grid



Refine it more to make it hexable



Suppress hanging nodes



Dualize to obtain a hexmesh

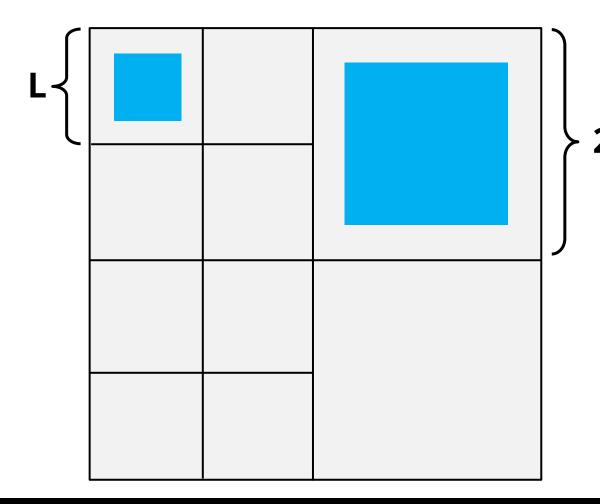






Requirements

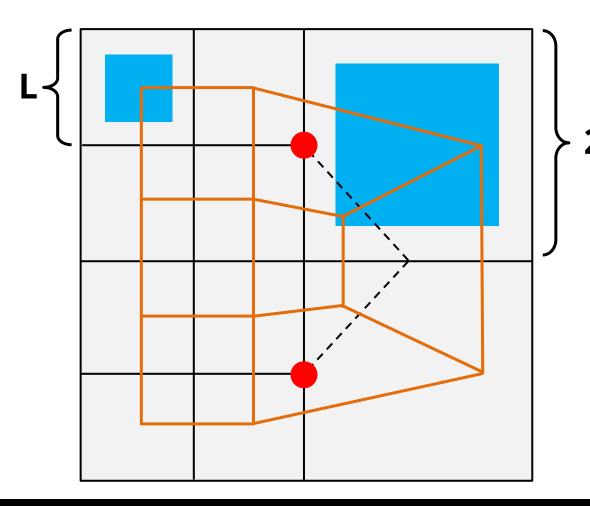
Hanging nodes can be suppressed only if two topological conditions are met



BALANCING: size mismatch for neighbors must be at most one

Requirements

Hanging nodes can be suppressed only if two topological conditions are met



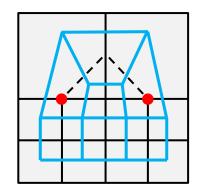
BALANCING: size mismatch for neighbors must be at most one

PAIRING: number of hanging nodes must be even along all sides

Transition schemes

Given a 3D adaptive grid that fulfills balancing and pairing, how to regularize vertex valence?

- ▶ In 2D:
 - each primal vertex with valence 4 yields a dual quad
 - one transition scheme handles all possible cases



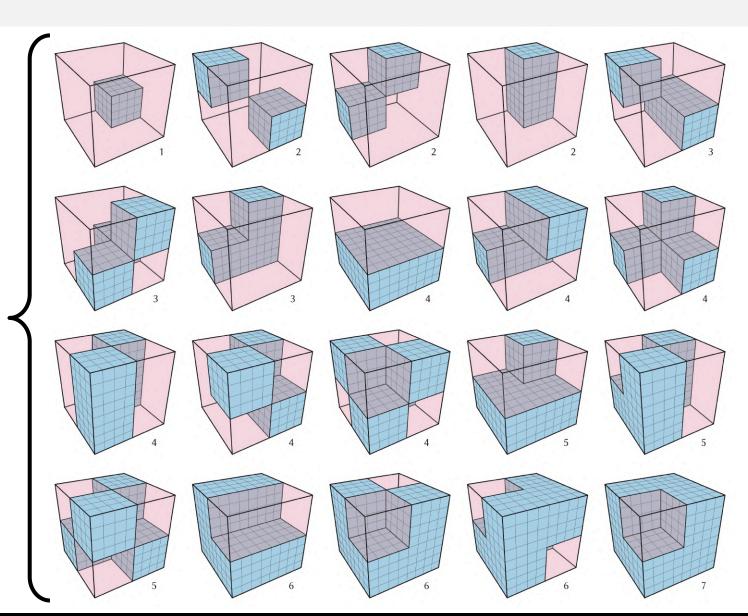
- ▶ In 3D:
 - each primal vertex with valence 6 yields a dual cell with 6 faces
 - each primal edge with valence 4 yields a dual quadrilateral face
 - more transition schemes are necessary

ALL HEX CONDITIONS

Combinatorics

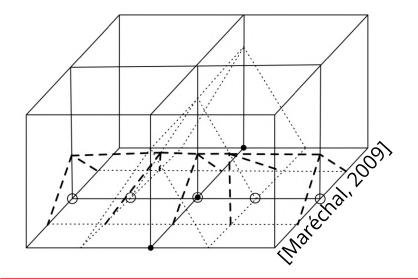
20
POSSIBLE
TRANSITIONS*

*assuming a BALANCED grid

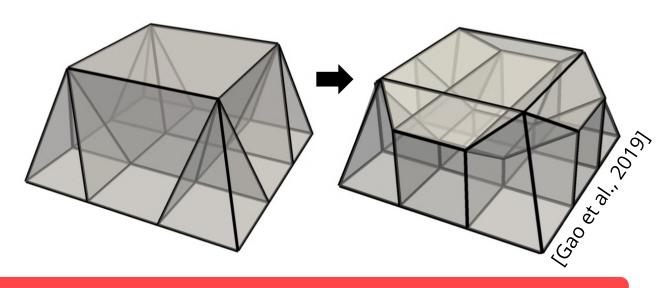


State of the art

REGULARIZE VERTEX/EDGE VALENCES VIA CELL CUTTING



DUALIZE FIRST, THEN SUBSTITUTE CLUSTERS OF HYBRID CELLS WITH HEXA



DO NOT NATIVELY COVER ALL 20 POSSIBLE TRANSITIONS

FLAT (4x4 to 2x2)

CONVEX EDGE

CONCAVE EDGE

CONCAVE CORNER

FLAT (4x4 to 2x2)

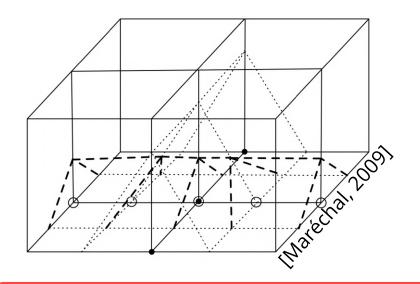
CONCAVE EDGE

CONVEX EDGE

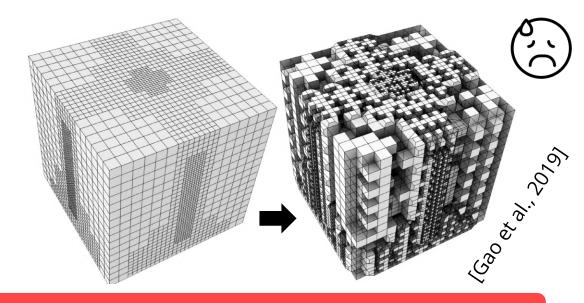
CONCAVE CORNER

State of the art

REGULARIZE VERTEX/EDGE VALENCES VIA CELL CUTTING



DUALIZE FIRST, THEN SUBSTITUTE CLUSTERS OF HYBRID CELLS WITH HEXA



DO NOT NATIVELY COVER ALL 20 POSSIBLE TRANSITIONS

FLAT (4x4 to 2x2)

CONVEX EDGE

CONCAVE EDGE

CONCAVE CORNER

FLAT (4x4 to 2x2)

CONVEX EDGE

CONCAVE EDGE

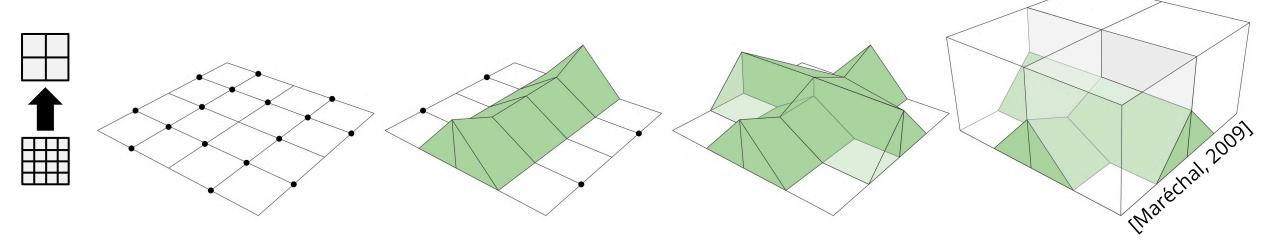
CONCAVE CORNER



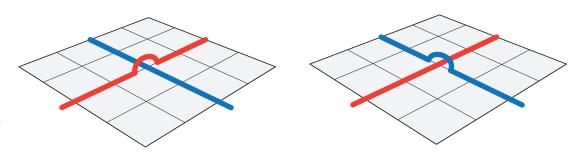
HEURISTIC CLUSTERING MAY FAIL

A dive into transitions

The idea is to suppress hanging nodes by *chains of prismatic elements* around clusters of refined cells

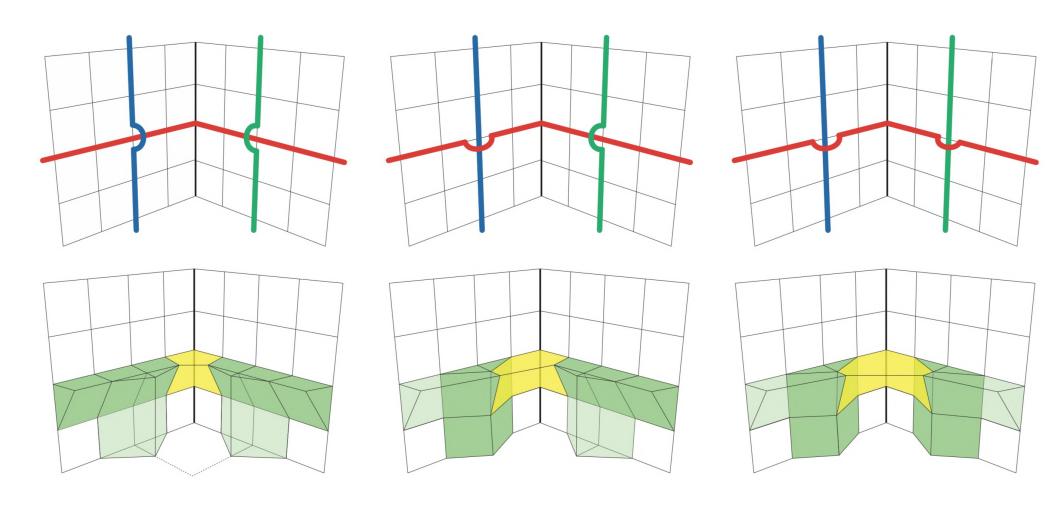


- schemes are internally asymmetric
 - which chain goes above and which below?
 - ambiguities in the implementation
 - unwanted effects on the singular structure



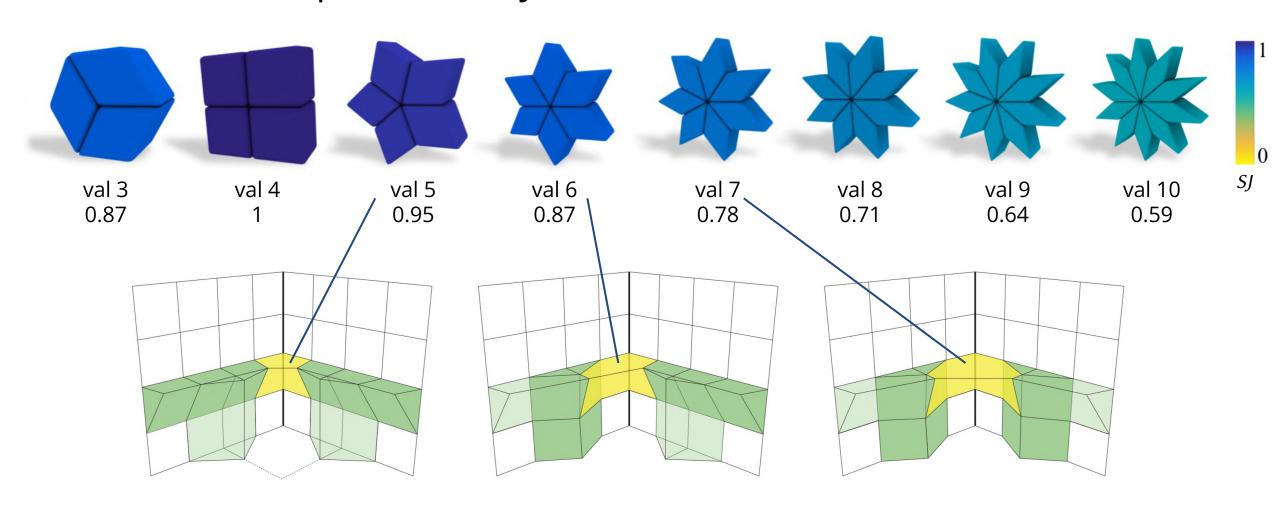
Concave edges

There are three possible ways to handle a concave transition



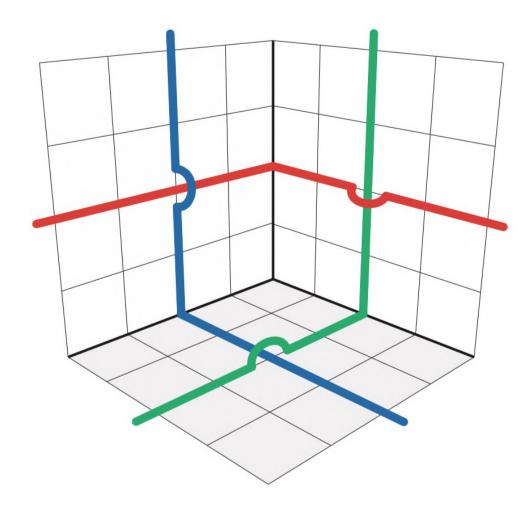
Concave edges

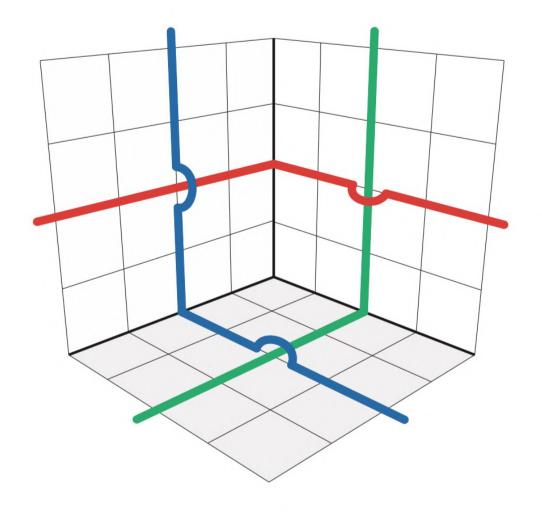
There are three possible ways to handle a concave transition



Concave corners

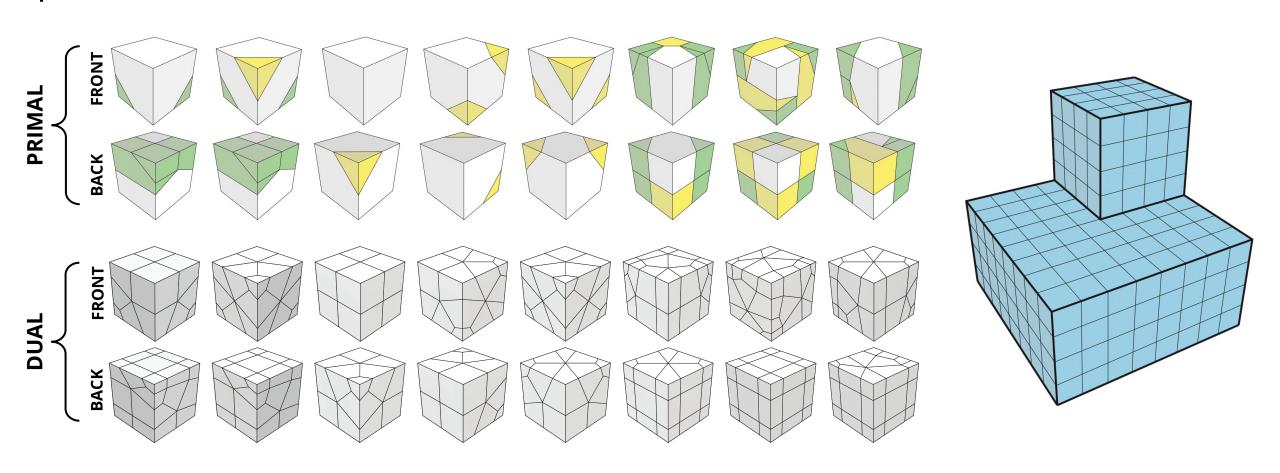
There are two possible ways to handle a concave corner





Reduced scheme set

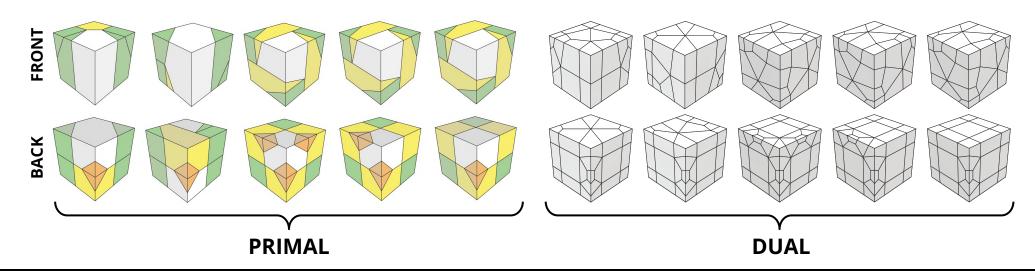
Eight *atomic building blocks* are sufficient to reproduce all 20 possible transitions



Extension to Weak Balancing

Balancing requires that adjacent cells differ by at most one level of refinement

- Strong balancing applies to face/edge/vert adjacent cells
- Weak balancing applies to face adjacent cells only
- ▶ **PRO:** achieve balancing with much less refinement
- ► **CON:** additional schemes for hybrid convex/concave edges

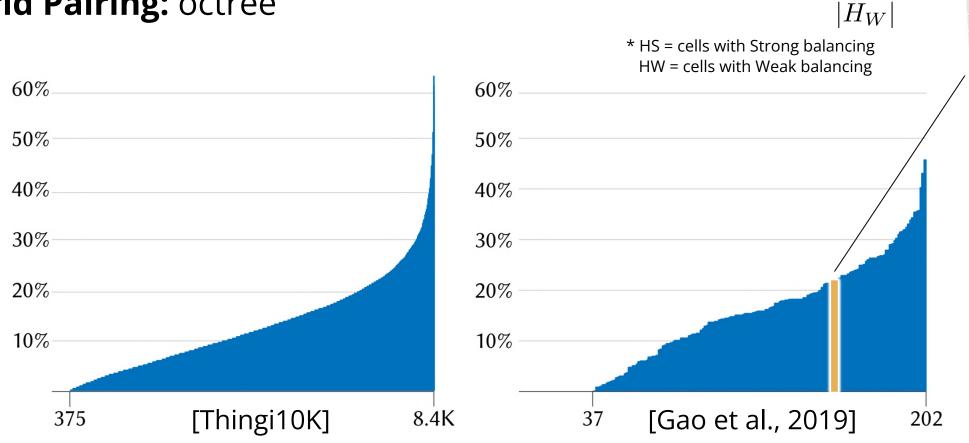


Validation, Analysis, Results



Strong vs Weak Balancing

- Input Grid: octree
- Refinement Policy: local thickness (SDF)
- ► **Grid Pairing:** octree

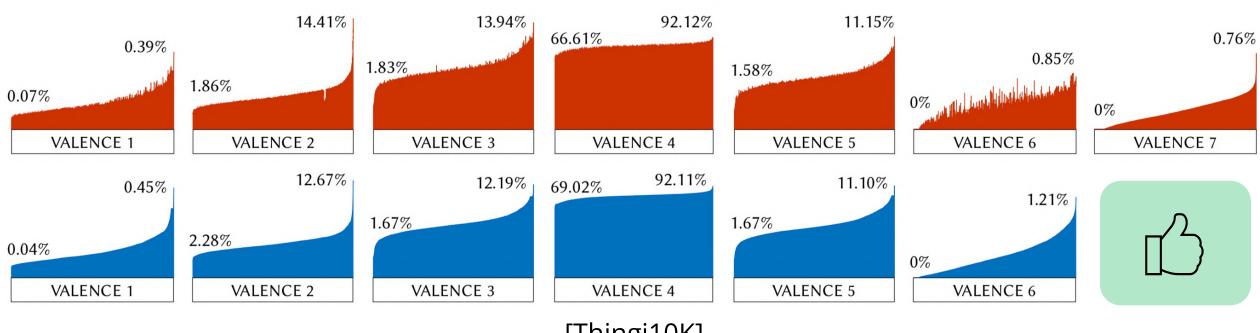


NORMALIZED RATIO

 $|H_S| - |H_W|$

Edge valences

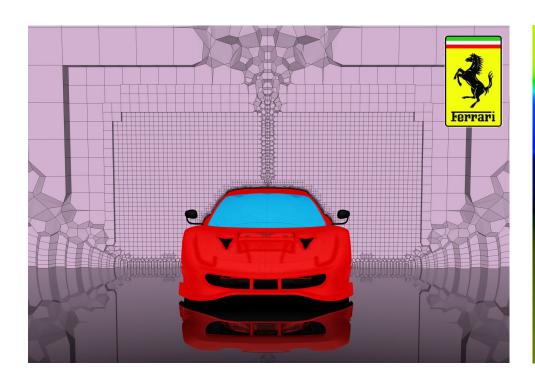
Optimal transition schemes, i.e., they handle intersections of prismatic elements to minimize per edge valence



[Thingi10K]

[Gao et al., 2019] fails in 37 models (not considered in the chart)

Are these improvements important?

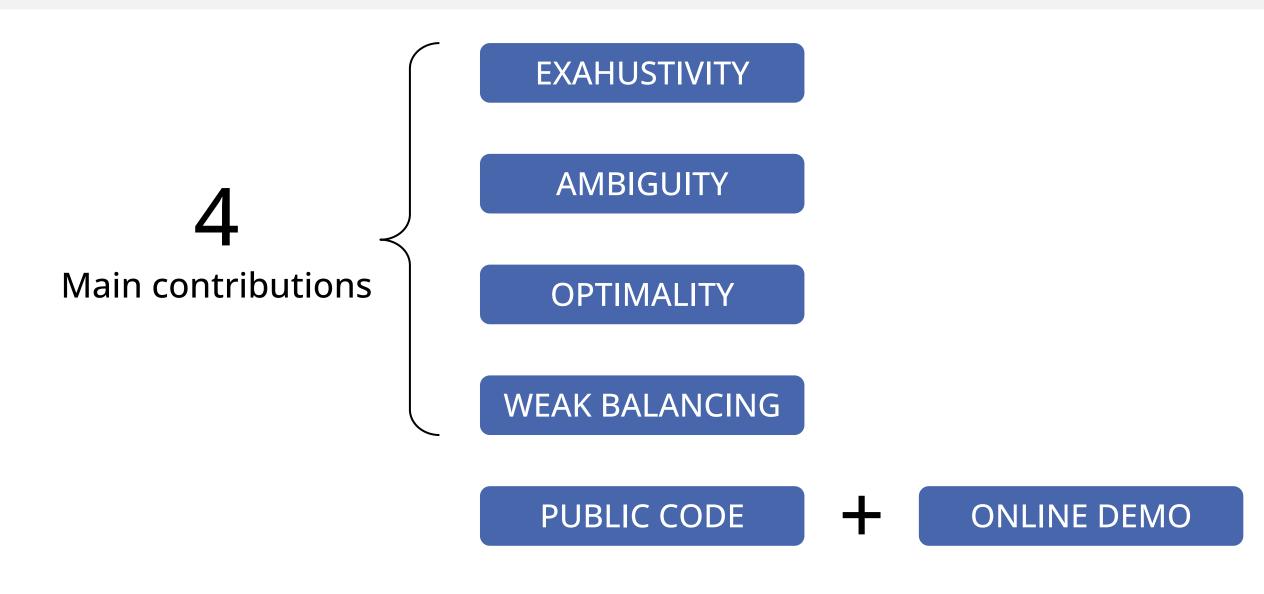




"Ferrari engineers used Mosaic enabled Poly-Hexcore meshing technology to **cut the number of cells by 15%**. This reduction [...] slashes overall solve times by half. The Ferrari team can now run **300% more CFD simulations**, helping the engineers to develop their cars or new solutions faster"



Conclusions





MARCO LIVESU CNR IMATI (Italy)



LUCA PITZALIS UNICA & CRS4 (Italy)



GIANMARCO CHERCHI University of Cagliari (Italy)





MORE INFO